

Online & Offline software at H.E.S.S.

ROOT User Workshop

15 October 2001

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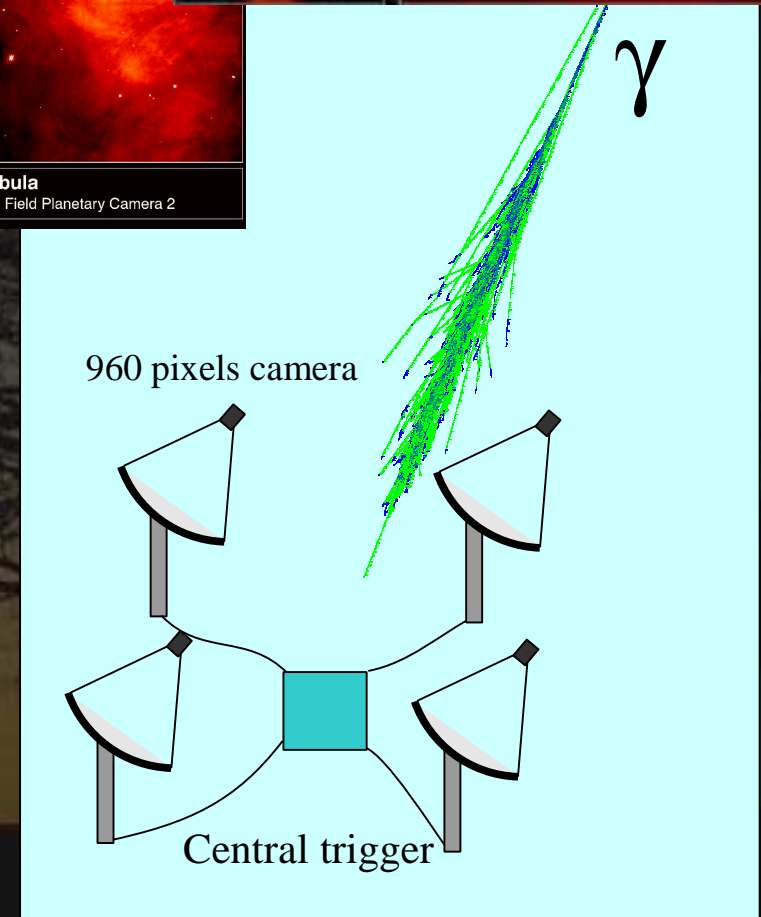
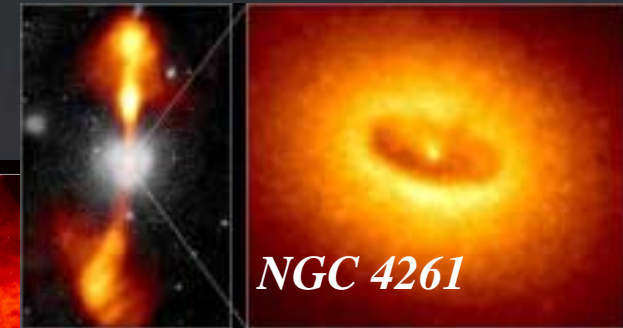
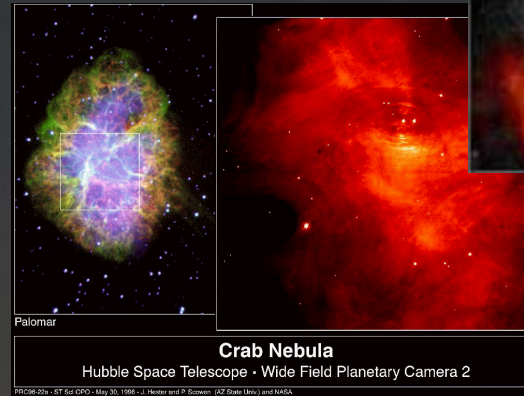
Christoph Borgmeier, Christian Stegmann, *Humboldt University Berlin*

- ♦ The H.E.S.S. Experiment
- ♦ Data storage & Off-line software
- ♦ Acquisition software
- ♦ ROOT Problems/Wishlist

<http://www.mpi-hd.mpg.de/hfm/HESS/HESS.html>

The High Energy Stereoscopic System (H.E.S.S.)

- ♦ Observe γ -induced showers above 100 GeV
 - ♦ Active galactic nuclei
 - ♦ Pulsars & Plerions
 - ♦ Micro-quasars
 - ♦ ...
- ♦ Stereoscopy for 3D reconstruction
- ♦ Fast camera & DAQ for threshold
- ♦ Installed in Namibia (Gamsberg)



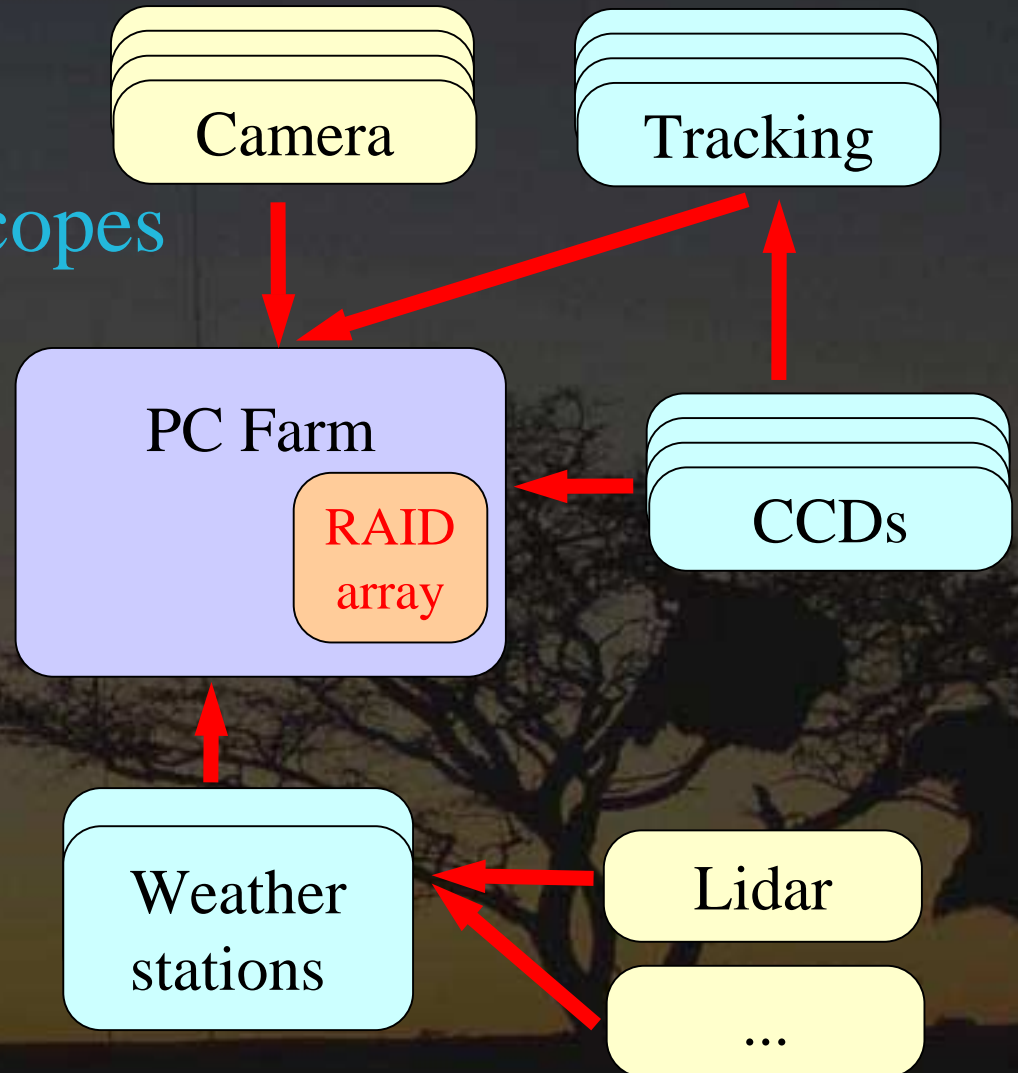
Current Status

- ◆ First telescope operational since June 2002
- ◆ Structure for the next 3
- ◆ Second camera : early 2003



Data sources @ H.E.S.S.

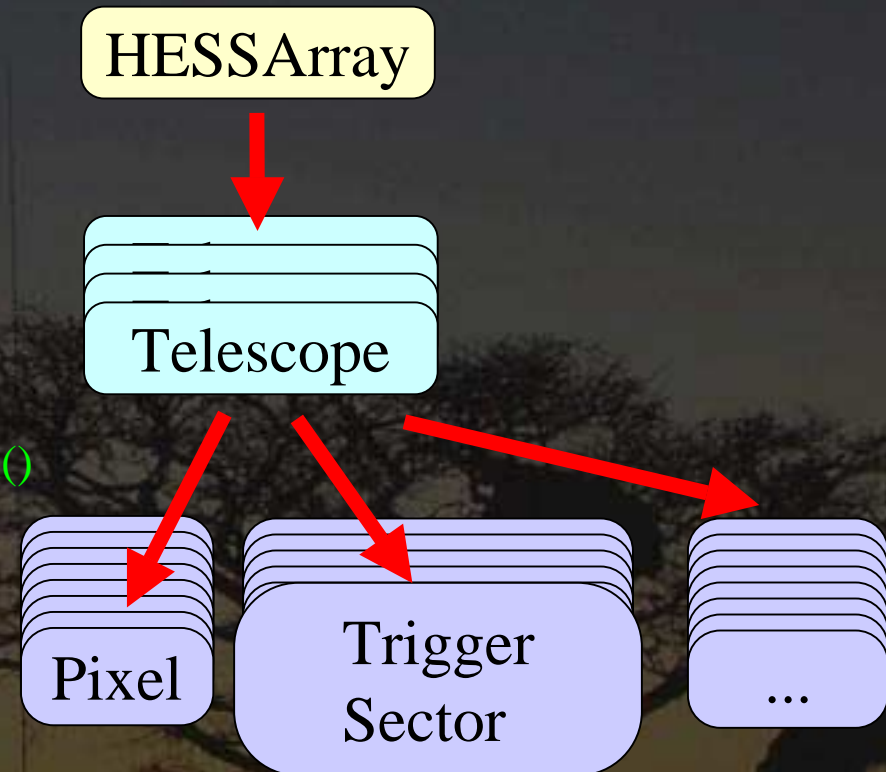
- ♦ Camera events: 1kHz
(6MB/s per camera)
- ♦ ~100 GB/night @ 4 telescopes
- ♦ Monitoring data
(taken independently)
 - ♦ CCDs
 - ♦ Cloud scanner
 - ♦ Optical Telescopes
 - ♦ Telescope drives
 - ♦



SASH: (*Storage & analysis software at H.E.S.S.*)

I – Container hierarchy

- ♦ Fixed container hierarchy
- ♦ No fixed numbering scheme
- ♦ All elements accessible from the top level container via iterators (no C pointers)
`Sash::Pointer<Sash::Pixel> Sash::Telescope::beginPixel()`
- ♦ List, Sets, ... and Iterator provided for looping over elements
`Sash::List<Sash::Pixel> Pixel::Neighbours()`



SASH

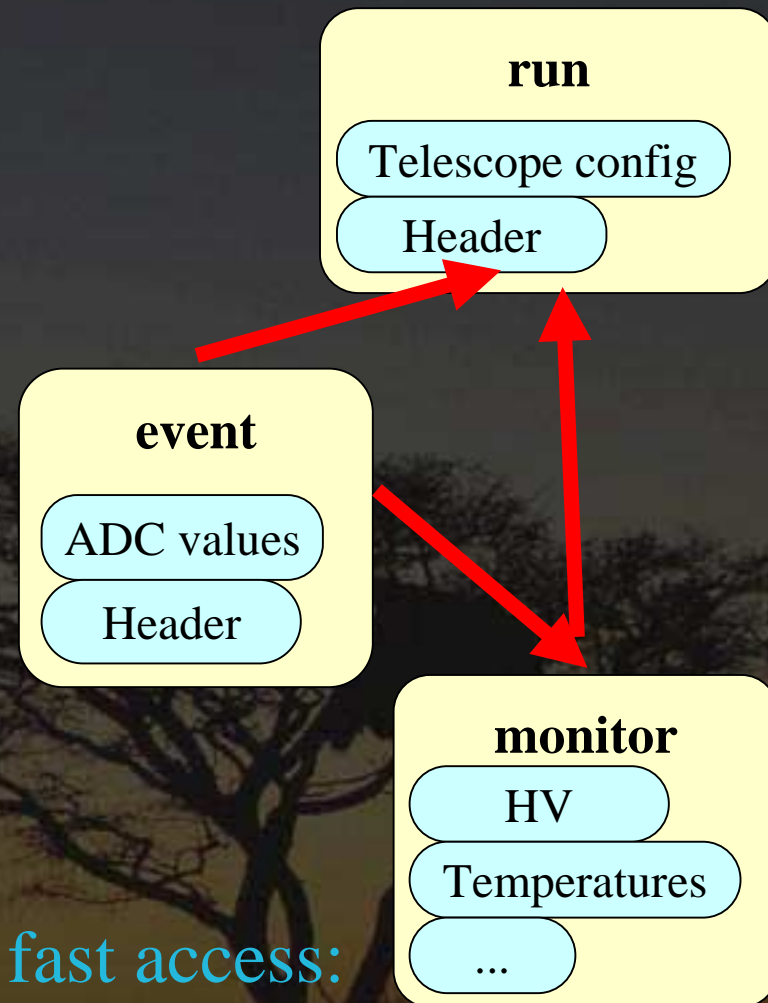
II – Data access

- ◆ Each data class knows its container type
- ◆ A helper template class registers a slot in the container for each data class
`Sash::EnvelopeEntry<T>`
- ◆ Additional **named** slots allows coexistence of several instances
(\Rightarrow comparison of analysis methods,...)
- ◆ Data classes are created and accessed by the container
(using CINT)
`Container::Handle<T>(parameters)` and `Get<T>()`
- ◆ Data classes store their creation parameters (argument of **Handle<T>**)
to enable automatic recreation at file readout
- ◆ Expandable (user class libraries)

SASH

III – Sash::DataSet

- ♦ Extension of ROOT TTree
 - ♦ Maps the data class at their proper location in the container hierarchy
 - ♦ Organises the data from the same TTree in TFolder (**run**, **events**, ...)
 - ♦ Provides iterators (iterate on events)
- ♦ Provides a **dependencies** mechanism based on time stamp from several files (monitor information is loaded for each event)
- ♦ Uses the branch splitting mechanism for fast access: **data are loaded only when accessed.**



SASH

IV – Sash::Makers

- ♦ Common interface for data manipulation
 - ♦ Receive a **Sash::DataSet** and operates on it
 - ♦ Full access to the container hierarchy
 - ♦ Can be chained + call-back mechanism
- ♦ Two specific Makers:
 - ♦ **Sash::DataSetIterator**: loads an event and synchronises other DataSets (monitor,...)
 - ♦ **Sash::TreeWriter**: writes a event to disk

DASH: *Data acquisition software*

- Multi-processes, multi-threaded & distributed acquisition

- CORBA (omniORB) for interprocess communication
(\Rightarrow modular, easily expandable)

- ROOT for storage & processing

- Python/Gtk for control

- ROOT or Python/Gtk for display

- Building blocks

- Buffer

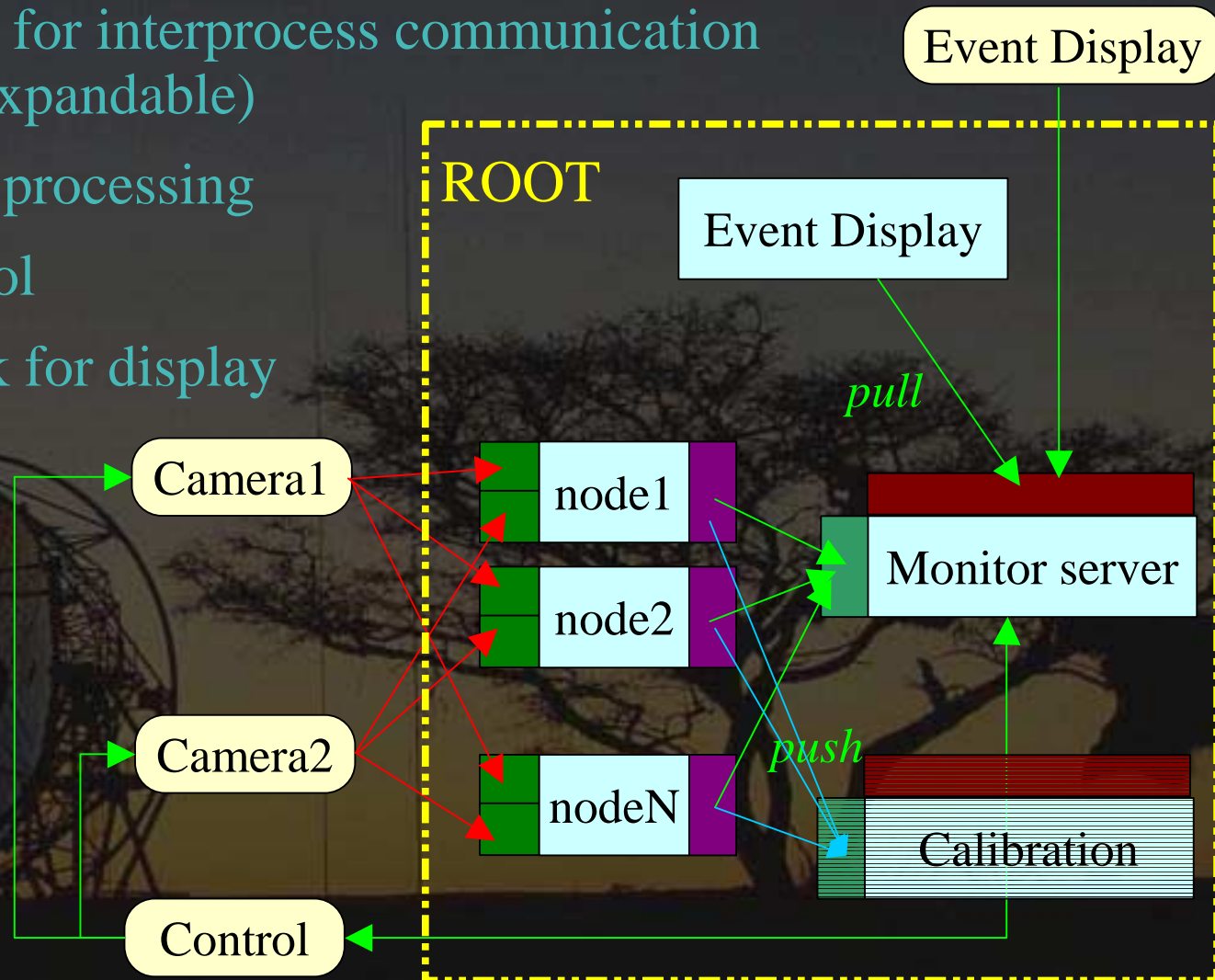
- Server

- Sender

- Processor

- ...

- Push & Pull

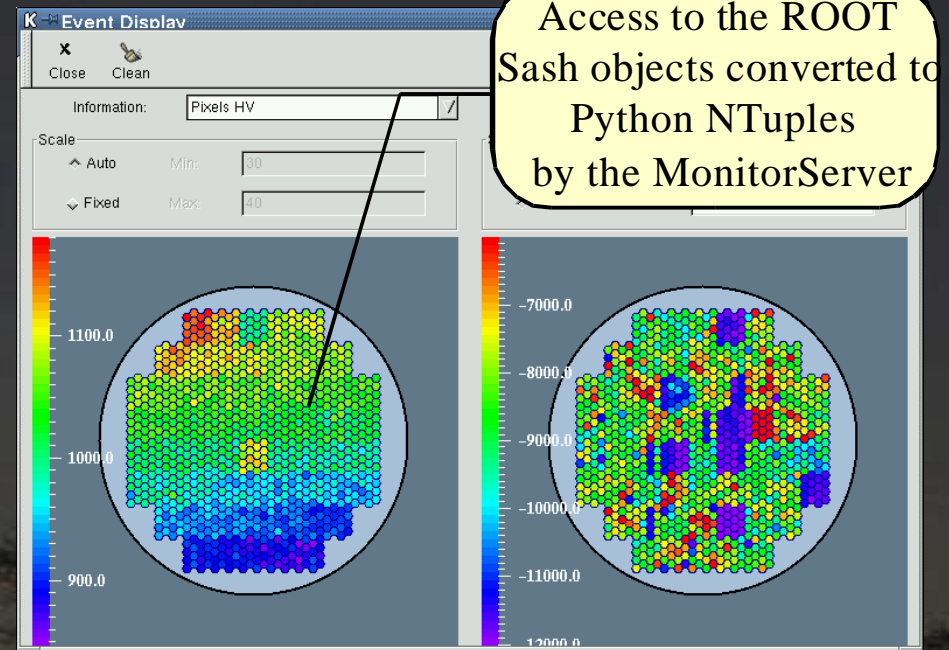
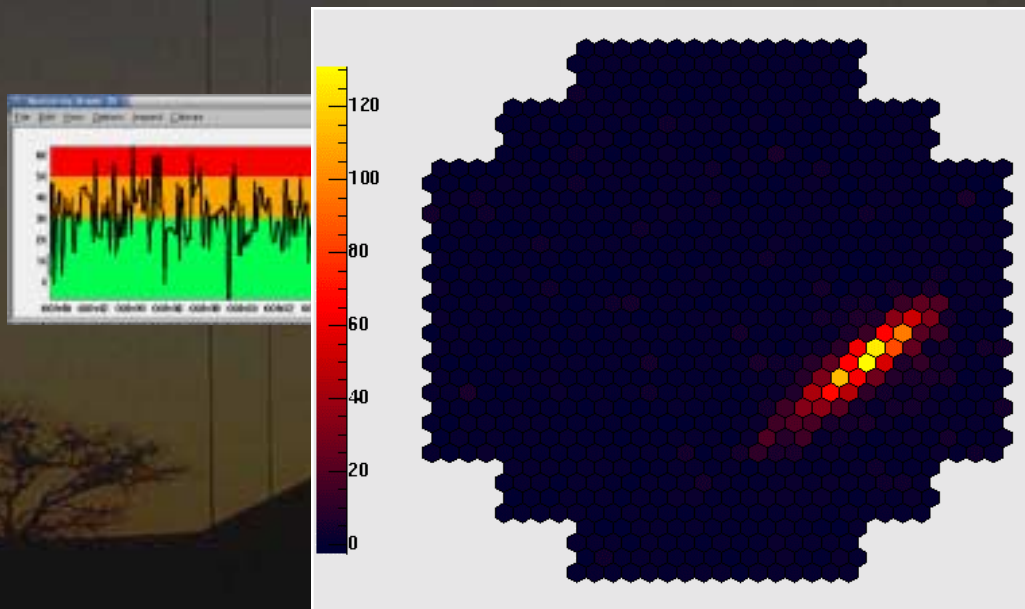


DASH II – Data Block Processor

- ♦ Arbitrary byte sequence data (\Rightarrow polymorphism)
 - ♦ CCD images or C Structures
 - ♦ Streamed ROOT objects
 - ♦ Whole folders
 - ♦ Automatic conversion into python arrays if corresponded function provided
- ♦ Data processed by **Processor_i**
- ♦ Three types of RootProcessor objects:
 - ♦ **RootProcessor_i**: arbitrary ROOT object, new memory location for each event
 - ♦ **FixedRootProcessor_i<T>**: non polymorphic but constant memory location
 - ♦ **HESSArrayProcessor_i**: maps the received objects/folders into the container hierarchy and call the registered **Sash::Maker**

Dash III - Displays

- ♦ Pull mode
- ♦ Process ask for a folder or a specific Sash object
- ♦ Use the **HESSArrayProcessor** to run **Sash::Maker's** for incoming objects



Summary

- ♦ Sash implements a general way to combine different ROOT trees (**Sash::DataSet**) from different files at a fixed memory location & automate tasks (**Sash::Maker**).
- ♦ Analysis/Calibration software consist of ~ 15 CVS modules based on Sash, ~ 10 developers
(many people develop their own analysis module)
- ♦ DASH provides a class hierarchy of building blocks to organize the H.E.S.S. DAQ in a general way
 - ♦ CORBA protocol \Rightarrow transparently expandable ressources
 - ♦ Modularity (building blocks connected by CORBA)
 - ♦ Transport of ROOT objects
 - ♦ Highly multithreaded data transport, display and analysis software
 - ♦ Good performances (6MB/s on a single machine)

ROOT Problems/Wishlist

Last year problems:

- ◆ Namespace support

Fixed

- ◆ Template support

Almost fixed

- ◆ STL support

much better

- ◆ Thread stability

improved

WhishList:

Better thread stability

Threads created by CORBA, not by ROOT.
Too much use of global variables in ROOT
(gFile,fgFitter,...)

Is Qt communication protocol thread-safe?

Support for templates member functions

```
class A {  
    template <class T> f();  
};  
#pragma link C++ function A::f<MyClass>();
```

Support for class member type change in ROOT I/O

(when cast operator or conversion constructor provided)

Experience with ROOT

- ◆ Impressive support from the ROOT team:
 - ◆ Quick fixes
 - ◆ Fast developpement of requested features

Thank you

